The Contents of Case 10610960

Qnum	Query	DB Name	Thesaurus	Operator	Plural
Q1	internal	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q2	Q1 same target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q3	external or surface	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q4	Q1 same Q2 same Q3	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q5	Q4 same (correlation or correlating or correlat$4 or match$4 or matching or matched)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q6	600/$.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q7	606/130.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q8	Q6 or Q7	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q9	Q5 and Q8	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q10	606/130.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q11	articulated same arm	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q12	surgical or probe or catheter or instrument	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q13	target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q14	robot	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q15	Q12 same Q13	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q16	Q11 same Q15	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q17	Q10 and Q16	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q18	Q16 and (robot or robotic or automatic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q19	Q18 and (robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q20	600/429.ccls.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q21	Q11 and Q20	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES
Q22	(robot or robotic)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE		ADJ	YES

Q23	Q21 and Q22	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q24	Q13 and Q23	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q25	changing same viewing sama trajectory	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q26	Q22 same (correcting or correction) same trajectory	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q27	Q20 and Q26	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q28	Q7 and Q22	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q29	Q28 and (target same trajectory)	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q30	intervening same view same target	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q31	Q30 and smith	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q32	6064904.uref.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q33	virtual and smith	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q34	Q20 and Q33	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q35	Ferre.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q36	Q20 and Q35	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q37	Q17 and deviation	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q38	deviation same trajectory	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q39	Q11 same Q38	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q40	"Van Der Burg"	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q41	Q40 and Q11	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q42	Q40 and robot	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q43	Van same Der same Brug	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q44	Q43 and Q11	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q45	5817105.pn.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q46	6112113.pn.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q47	Van Der Brug.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q48	glassman.inv.	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES
Q49	Q48 and	PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD ASSIGNEE	ADJ	YES